Adaptive Federated Learning with Auto-tuned Clients via Local Smoothness

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Federated Learning Overview

- FL is a recent distributed machine learning framework where a global model is trained via multiple collaborative steps by participating clients without sharing data.
- Mathematically, we want to solve

$$\min_{x \in \mathbb{R}^d} f(x) = \frac{1}{m} \sum_{i=1}^m f_i(x)$$

where $x \in \mathbb{R}^d$ is the shared model parameter, m is the number of clients, and $f_i(x) := \mathbb{E}_{z \sim \mathcal{D}_i}[F_i(x,z)]$ is the individual loss function.

• Offers flexible collaborative learning: the number of clients m, their participation rates, and the computing power can all vary and change at any point during the overall training procedure.

$$f_i(x) \leftarrow \mathbb{E}_{z \sim \mathcal{D}_i}[F_i(x, z)]$$

• Therefore, not only \mathcal{D}_i differs for each client i, but also the number of samples $z \sim \mathcal{D}_i$, resulting in each client having different $f_i(\cdot)$.

Challenges in Federated Learning

Algorithm FedAvg 1: **input**: $x_0 \in \mathbb{R}^d$, $\eta > 0$, and $p \in (0, 1)$. 2: **for** each round t = 0, 1, ..., T-1 **do** sample a subset S_t of clients with size $|S_t| = p \cdot m$ for each machine in parallel for $i \in \mathcal{S}_t$ do Set $x_{t,0}^i = x_t$ for local step $k \in [K]$ do 6: Compute an estimate $g_{t,k-1}^i$ of $\nabla f_i(x_{t,k-1}^i)$ $x_{t,k}^i = x_{t,k-1}^i - \eta g_{t,k-1}^i$ end for 9: end for 10: $x_{t+1} = \frac{1}{|\mathcal{S}_t|} \sum_{i \in \mathcal{S}_t} x_{t,K}^i = x_t - \frac{1}{|\mathcal{S}_t|} \sum_{i \in \mathcal{S}} (x_t - x_{t,K}^i)$ 11: 12: end for 13: **return** x_T

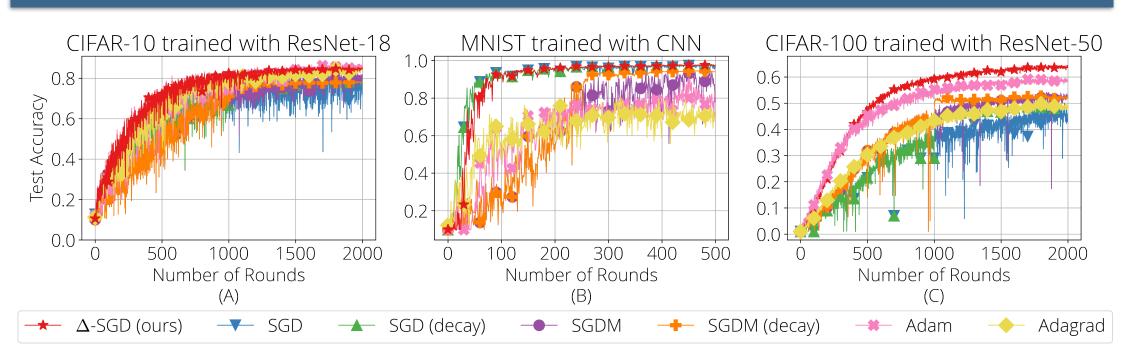
Server-side: How do we smartly aggregate the local information coming from each participating client?

- Federated Averaging [McMahan et al., 2017] uses simple averaging
- [Reddi et al., 2021] interpreted averaging as a "pseudo-gradient" step and introduced FedAdam, FedYogi, FedAdagrad, etc.

Client-side: How do we make sure each client meaningfully "learns" using local data?

- Federated Averaging [McMahan et al., 2017] uses SGD.
- Does it make sense to use the same η for all clients? If not, how should we tune individual step sizes?
- Important to properly tune: many more local updates compared to the aggregation step, as communication is much more expensive.

Client Optimization Is More Challenging?



- We fine-tune the step size for each client optimizer in task (A), and intentionally keep it the same for the other tasks, to highlight the effect of not properly tuning the step size of each client optimizer. Our proposed method, Δ -SGD, exhibits superior performance in all settings, without any additional tuning.
- (A): CIFAR-10 classification task trained on ResNet-18. (B): MNIST classification task trained on shallow CNN. (C): CIFAR-100 classification task trained on ResNet-50.
- All experiments use FedAvg as the server optimizer.

Why is the step size $\eta = 1/L$ popular?

- L-smooth functions: $f(y) \le f(x) + \langle \nabla f(x), y x \rangle + \frac{L}{2} ||y x||^2 \ \forall x, y$
- Gradient descent: $x_{t+1} = x_t \eta \nabla f(x_t)$
- Descent lemma:

$$f(x_{t+1}) \le f(x_t) + \langle \nabla f(x_t), x_{t+1} - x_t \rangle + \frac{L}{2} ||x_{t+1} - x_t||^2$$

= $f(x_t) - \eta \left(1 - \frac{\eta \cdot L}{2}\right) ||\nabla f(x_t)||^2$

• $\eta = 1/L$ maximizes the descent progress.

Adaptive Step Size via Local Smoothness

• [Malisky & Mishchenko, 2020] proposed the following step size for (centralized) gradient descent:

$$\eta_t = \min \left\{ \frac{\|x_t - x_{t-1}\|}{2\|\nabla f(x_t) - \nabla f(x_{t-1})\|}, \sqrt{1 + \frac{\eta_{t-1}}{\eta_{t-2}}} \eta_{t-1} \right\}$$

• The first condition approximates the local smoothness

$$\|\nabla f(x_t) - \nabla f(x_{t-1})\| \le L_t \cdot \|x_t - x_{t-1}\|, \quad \forall t = 1, 2, \dots$$

and the second condition ensures η_t to not increase too fast.

• We adapt the above step size to the FL setting:

$$\eta_{t,k}^{i} = \min \left\{ \frac{\|x_{t,k}^{i} - x_{t,k-1}^{i}\|}{2\|\tilde{\nabla}f_{i}(x_{t,k}^{i}) - \tilde{\nabla}f_{i}(x_{t,k-1}^{i})\|}, \sqrt{1 + \frac{\eta_{t,k}^{i}}{\eta_{t,k-1}^{i}}} \eta_{t,k-1}^{i} \right\}$$

with the stochastic gradients $\nabla f_i(\cdot)$ and the local iterations k.

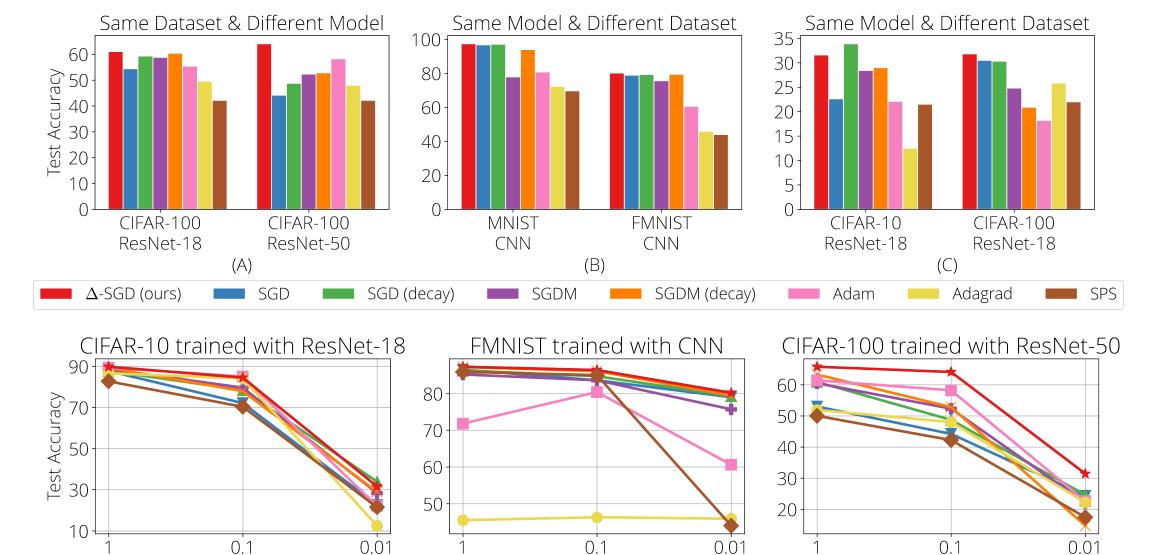
• Implication: each client uses its own step size η_t^l that is adaptive to the local smoothness of $f_i(\cdot)$

Experimental Results: Δ -SGD exhibits superior performance in all settings without any additional tuning

Dirichlet Parameter α

Non-iidness	Optimizer	Dataset / Model				
$\mathrm{Dir}(lpha\cdot\mathbf{p})$		MNIST CNN	FMNIST CNN	CIFAR-10 ResNet-18	CIFAR-100 ResNet-18	CIFAR-100 ResNet-50
$\alpha = 1$	SGD SGD (↓) SGDM SGDM (↓) Adam Adagrad SPS Δ-SGD	$98.3_{\downarrow(0.2)}$ $97.8_{\downarrow(0.7)}$ $98.5_{\downarrow(0.0)}$ $98.4_{\downarrow(0.1)}$ $94.7_{\downarrow(3.8)}$ $64.3_{\downarrow(34.2)}$ $10.1_{\downarrow(88.4)}$ $98.4_{\downarrow(0.1)}$	$86.5_{\downarrow(0.8)}$ $86.3_{\downarrow(1.0)}$ $85.2_{\downarrow(2.1)}$ $87.2_{\downarrow(0.1)}$ $71.8_{\downarrow(15.5)}$ $45.5_{\downarrow(41.8)}$ $85.9_{\downarrow(1.4)}$ $87.3_{\downarrow(0.0)}$	$87.7_{\downarrow(2.1)}$ $87.8_{\downarrow(2.0)}$ $88.7_{\downarrow(1.1)}$ $89.3_{\downarrow(0.5)}$ $89.4_{\downarrow(0.4)}$ $86.6_{\downarrow(3.2)}$ $82.7_{\downarrow(7.1)}$	$57.7_{\downarrow(4.2)}$ $61.9_{\downarrow(0.0)}$ $58.8_{\downarrow(3.1)}$ $61.4_{\downarrow(0.5)}$ $55.6_{\downarrow(6.3)}$ $53.5_{\downarrow(8.4)}$ $1.0_{\downarrow(60.9)}$	$53.0_{\downarrow(12.8)}$ $60.9_{\downarrow(4.9)}$ $60.5_{\downarrow(5.3)}$ $63.3_{\downarrow(2.5)}$ $61.4_{\downarrow(4.4)}$ $51.9_{\downarrow(13.9)}$ $50.0_{\downarrow(15.8)}$
$\alpha = 0.1$	SGD SGD (↓) SGDM SGDM (↓) Adam Adagrad SPS Δ-SGD	$98.1_{\downarrow(0.0)}$ $98.0_{\downarrow(0.1)}$ $97.6_{\downarrow(0.5)}$ $98.0_{\downarrow(0.1)}$ $96.4_{\downarrow(1.7)}$ $89.9_{\downarrow(8.2)}$ $96.0_{\downarrow(2.1)}$	$83.6_{\downarrow(2.8)}$ $84.7_{\downarrow(1.7)}$ $83.6_{\downarrow(2.8)}$ $86.1_{\downarrow(0.3)}$ $80.4_{\downarrow(6.0)}$ $46.3_{\downarrow(40.1)}$ $85.0_{\downarrow(1.4)}$	$72.1_{\downarrow(12.9)}$ $78.4_{\downarrow(6.6)}$ $79.6_{\downarrow(5.4)}$ $77.9_{\downarrow(7.1)}$ $85.0_{\downarrow(0.0)}$ $84.1_{\downarrow(0.9)}$ $70.3_{\downarrow(14.7)}$	$54.4_{\downarrow(6.7)}$ $59.3_{\downarrow(1.8)}$ $58.8_{\downarrow(2.3)}$ $60.4_{\downarrow(0.7)}$ $55.4_{\downarrow(5.7)}$ $49.6_{\downarrow(11.5)}$ $42.2_{\downarrow(18.9)}$	$44.2_{\downarrow(19.9)}$ $48.7_{\downarrow(15.4)}$ $52.3_{\downarrow(11.8)}$ $52.8_{\downarrow(11.3)}$ $58.2_{\downarrow(5.9)}$ $48.0_{\downarrow(16.1)}$ $42.2_{\downarrow(21.9)}$ $64.1_{\downarrow(0.0)}$
$\alpha = 0.01$	SGD SGD (↓) SGDM SGDM (↓) Adam Adagrad SPS Δ-SGD	$96.8_{\downarrow(0.7)}$ $97.2_{\downarrow(0.3)}$ $77.9_{\downarrow(19.6)}$ $94.0_{\downarrow(3.5)}$ $80.8_{\downarrow(16.7)}$ $72.4_{\downarrow(25.1)}$ $69.7_{\downarrow(27.8)}$	$79.0_{\downarrow(1.2)}$ $79.3_{\downarrow(0.9)}$ $75.7_{\downarrow(4.5)}$ $79.5_{\downarrow(0.7)}$ $60.6_{\downarrow(19.6)}$ $45.9_{\downarrow(34.3)}$ $44.0_{\downarrow(36.2)}$ $80.2_{\downarrow(0.0)}$	$22.6_{\downarrow(11.3)}$ $33.9_{\downarrow(0.0)}$ $28.4_{\downarrow(5.5)}$ $29.0_{\downarrow(4.9)}$ $22.1_{\downarrow(11.8)}$ $12.5_{\downarrow(21.4)}$ $21.5_{\downarrow(12.4)}$ $31.6_{\downarrow(2.3)}$	$30.5_{\downarrow(1.3)}$ $30.3_{\downarrow(1.5)}$ $24.8_{\downarrow(7.0)}$ $20.9_{\downarrow(10.9)}$ $18.2_{\downarrow(13.6)}$ $25.8_{\downarrow(6.0)}$ $22.0_{\downarrow(9.8)}$ $31.8_{\downarrow(0.0)}$	$24.3_{\downarrow(7.1)}$ $24.6_{\downarrow(6.8)}$ $22.0_{\downarrow(9.4)}$ $14.7_{\downarrow(16.7)}$ $22.6_{\downarrow(8.8)}$ $22.2_{\downarrow(9.2)}$ $17.4_{\downarrow(14.0)}$ $31.4_{\downarrow(0.0)}$

- We examine the performance difference when we change the dataset, model architecture, or level of heterogeneity induced by the Dirichlet concentration parameter α .
- Step size for each client optimizer is fine-tuned for CIFAR-10 classification task trained with ResNet-18, with $\alpha=0.1$.



Dirichlet Parameter α

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